



Master / Bachelor Thesis

Using dynamic priority assignment to increase feasibility in prioritybased networked control

Problem Statement

The project GROKO-Plan aims at developing a graph-based planning method for optimal cooperative trajectories for interacting vehicles. In a broad sense, the goal of trajectory planning is to find a sequence of control inputs that take a vehicle from a starting position to an end position.

The optimal solution of the trajectory planning problem for a system consisting of multiple agents can be obtained when formulating the centralized control problem that considers all agents. If a solution to the problem exists, it can be obtained in the centralized formulation, at the cost of high computatioal load. The computational load can be reduced by a distribution of the control problem among the agents. Wether the distributed control problem is feasible depends highly on the priority assignment. Consider the situation in Figure 1 where three vehicles follow a straight reference trajectory and encounter an obstacle.

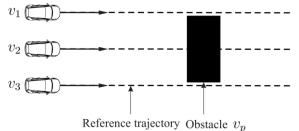




FIGURE 1 PRIORITY ASSIGNMENT PROBLEM OF THREE VEHICLES DRIVING IN FORMATION.

Assume that the vehicles drive with constant velocity and can only use steering as a control input. Given a priority order of 1, 2, and 3, there are six possibilities for priority assignment. Four of them are valid, but if v_2 has the lowest priority, the vehicle cannot find a feasible solution to its control problem.

Task

- Analyze existing strategies for priority distribution
- Develop strategies for priority distribution with the goal of increasing feasibility of the distributed control problem
- Apply the developed strategies for priority distribution to trajectory planning for ground vehicles in an urban scenario
- Evaluate the developed strategies with 20 model-scale vehicles in the <u>CPM Lab</u>

Qualifications

- Knowledge of MATLAB and/or C++
- Affinity to mathematics
- Student of Automation Engineering, Computer Science, Mechanical Engineering, Electrical Engineering or a similar study program

Contact

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