

Dr.-Ing. Alexandru Kampmann

Member of the [Cyber-physical Mobility Group](#)

Contact

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Research Associate / PhD Candidate



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Office: 2225

About

As a member of the [Cyber-physical Mobility Group](#), I am researching automotive-grade service-oriented software architectures in the context of the [UNICARagil](#) project.

Bachelor/Master Thesis

If you are interested in a Bachelor's or Master's thesis, please contact me by e-mail. Your own suggestions are also possible.

Open HiWi/WiHi Positions

Current vacancies can be found [here](#). Unsolicited applications are also welcome. Applications should include a grade overview and a short CV.

Patents

- [Methods and systems for opening of a vehicle access point using audio or video data associated with a user](#)
- [Passenger tracking systems and methods](#)
- [Inductive loop detection systems and methods](#)
- [Pedestrian detection when a vehicle is reversing](#)
- [Sinkhole detection systems and methods](#)
- [Detecting hazards in anticipation of opening vehicle doors](#)
- [Rear camera stub detection](#)
- [Accident attenuation systems and methods](#)
- [Lane detection systems and methods](#)
- [Vehicle localization using cameras](#)

Publications

[GRB+24]

PDFBIB

Goldermann, L., Rakel, S., Buglowski, M., Mokhtarian, A., Kampmann, A., Janß, A., Yilmaz, O., Beger, F., Walter, M., Leonhardt, S., Kowalewski, S., and Stollenwerk, A., "Designing the user interface of a ventilator under the constraints of a pandemic", *Automatisierungstechnik*, vol. 72, iss. 5, pp. 484-495, 2024

Designing the user interface of a ventilator under the constraints of a pandemic

Bibtex entry :

```
@article { GRB+24,
  author = { Goldermann, Lavinia and Rakel, Stefan and Buglowski, Mateusz
            and Mokhtarian, Armin and Kampmann, Alexandru and Jan{\ss}, Armin and Yilmaz, Okan and Beger, Frank and Walter, Marian and Leonhardt, Steffen and Kowalewski, Stefan and Stollenwerk, André },
  title = { Designing the user interface of a ventilator under the constraints of a pandemic },
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journal = { Automatisierungstechnik },
publisher = { De Gruyter },
pages = { 484-495 },
volume = { 72 },
number = { 5 },
year = { 2024 },
address = { Berlin },
issn = { 0178-2312 },
doi = { 10.1515/auto-2023-0205 },
typ = { PUB:(DE-HGF)16 },
reportid = { RWTH-2024-04857 },
cin = { 122810 / 611010 / 419410 / 120000 },
}

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[BMA+23]

[PDFBIB](#)

Böhlen, B., Meyer, O., Alrifaae, B., Beerwerth, J., Kampmann, A., Kowalewski, S., Konersmann, M., Rumpe, B., and Steinfurth, F., "Software-Defined Vehicle - Herausforderungen in der Diagnose dienstorientierter Fahrzeugarchitekturen", in *Proc. Diagnose in mechatronischen Fahrzeugsystemen XVI : Software-Defined Vehicle, SOVD, Maschinelles Lernen und KI, Standardisierung, HU und ADAS / Prof. Dr. Bernard Bäker, Dipl.-Ing. Andreas Unger (Hrsg.) und 53 Mitautoren*, Dresden, 2023, TUDpress, pp. 17-28.

Software-Defined Vehicle - Herausforderungen in der Diagnose dienstorientierter Fahrzeugarchitekturen

Bibtex entry :

```

@inproceedings { BMA+23,
  author = { B{"o}hlen, Boris and Meyer, Oliver and Alrifaae, Bassam
and
  Beerwerth, Julius and Kampmann, Alexandru and Kowalewski,
Stefan and Konersmann, Marco and Rumpe, Bernhard and
Steinfurth, Felix },
  title = { Software-Defined Vehicle – Herausforderungen in der
  Diagnose dienstorientierter Fahrzeugarchitekturen },
  booktitle = { Diagnose in mechatronischen Fahrzeugsystemen XVI :
  Software-Defined Vehicle, SOVD, Maschinelles Lernen und KI,
  Standardisierung, HU und ADAS / Prof. Dr. Bernard B{"a}ker,
  Dipl.-Ing. Andreas Unger (Hrsg.) und 53 Mitautoren },
  publisher = { TUDpress },
  pages = { 17-28 },
  year = { 2023 },
  address = { Dresden },
  organization = { 16. Tagung Diagnose in mechatronischen
Fahrzeugsystemen,
  Dresden (Germany), 2023-05-23 - 2023-05-24 },
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  reportid = { RWTH-2023-10164 },
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url = {  
http://publications.rwth-aachen.de/record/972417/files/972417.pdf },  
  illkey = { BMBF 01IS22088A - Verbundprojekt MANNHEIM-AUT0tech.agil:  
  Architektur und Technologien zur Orchestrierung  
  automobiltechnischer Agilit{"a"}t (01IS22088A) },  
}
```

[Kam23]

[PDFBIB](#)

Kampmann, A., "A dynamic service-oriented software architecture for the automotive domain", PhD Thesis, Aachen, 2023.

A dynamic service-oriented software architecture for the automotive domain

Bibtex entry :

```
@phdthesis { Kam23,  
  author = { Kampmann, Alexandru },  
  othercontributors = { Kowalewski, Stefan and Eckstein, Lutz },  
  title = { A dynamic service-oriented software architecture for the  
  automotive domain },  
  publisher = { RWTH Aachen University },  
  school = { RWTH Aachen University },  
  pages = { 1 Online-Ressource : Illustrationen },  
  series = { Aachener Informatik-Berichte (AIB) },  
  year = { 2023 },  
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  doi = { 10.18154/RWTH-2024-00864 },  
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http://publications.rwth-aachen.de/record/977648/files/977648.pdf },  
}
```

[KLK+22]

[PDFBIB](#)

Kampmann, A., Lürer, M., Kowalewski, S., and Alrifaae, B., "Optimization-based Resource Allocation for an Automotive Service-oriented Software Architecture", in *Proc. 2022 IEEE Intelligent Vehicles Symposium (IV) : 4-9 June 2022 / publisher: IEEE, Piscataway, NJ, 2022, IEEE*, pp. 678-687.

Optimization-based Resource Allocation for an Automotive Service-oriented Software Architecture

Bibtex entry :

```
@inproceedings { KLK+22,
```

```

author = { Kampmann, Alexandru and L{"u}er, Maximilian and
Kowalewski,
    Stefan and Alrifaae, Bassam },
title = { Optimization-based Resource Allocation for an Automotive
Service-oriented Software Architecture },
booktitle = { 2022 IEEE Intelligent Vehicles Symposium (IV) : 4-9
June
    2022 / publisher: IEEE },
publisher = { IEEE },
pages = { 678-687 },
year = { 2022 },
address = { Piscataway, NJ },
organization = { 33. IEEE Intelligent Vehicles Symposium, Aachen
(Germany),
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doi = { 10.1109/IV51971.2022.9827429 },
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http://publications.rwth-aachen.de/record/853127/files/853127.pdf },
}

```

[KLP+22]

[PDFBIB](#)

Kampmann, A., Lamberti, M., Petrovic, N., Kowalewski, S., and Alrifaae, B., "Investigating Outdoor Recognition Performance of Infrared Beacons for Infrastructure-based Localization", in *Proc. 2022 IEEE Intelligent Vehicles Symposium (IV) : 4-9 June 2022 / publisher: IEEE*, Piscataway, NJ, 2022, IEEE, pp. 1107-1113.

Investigating Outdoor Recognition Performance of Infrared Beacons for Infrastructure-based Localization

Bibtex entry :

```

@inproceedings { KLP+22,
author = { Kampmann, Alexandru and Lamberti, Michael and Petrovic,
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title = { Investigating Outdoor Recognition Performance of Infrared
    Beacons for Infrastructure-based Localization },
booktitle = { 2022 IEEE Intelligent Vehicles Symposium (IV) : 4-9
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cin = { 122810 / 120000 },
url = {
http://publications.rwth-aachen.de/record/853126/files/853126.pdf },
}
```

[KMK+22]

PDFBIB

Kampmann, A., Mokhtarian, A., Kowalewski, S., and Alrifaae, B., "ASOA - A Dynamic Software Architecture for Software-defined Vehicles", in *Proc. [31st Aachen Colloquium Sustainable Mobility 2022]*, 2022.

ASOA - A Dynamic Software Architecture for Software-defined Vehicles

Bibtex entry :

```
@inproceedings { KMK+22,
  author = { Kampmann, Alexandru and Mokhtarian, Armin and
Kowalewski,
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defined
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  booktitle = { [31st Aachen Colloquium Sustainable Mobility 2022] },
  year = { 2022 },
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  url = {
http://publications.rwth-aachen.de/record/856836/files/856836.pdf },
}
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[JSG+21]

PDFBIB

Jatzkowski, I., Stolte, T., Graubohm, R., Maurer, M., Kampmann, A., Alrifaae, B., Kowalewski, S., Buchholz, M., and Dietmayer, K., "Integration of a Vehicle Operating Mode Management into UNICARagil's Automotive Service-oriented Software Architecture", in *Proc. 30. Aachen Colloquium Sustainable Mobility : October 4th-6th, 2021 / scientific management: Univ.-Prof. Dr.-Ing. Lutz Eckstein, Univ.-Prof. Dr.-Ing. Stefan Pischinger ; organizational management: Michaela Wacker (M. Sc.), Jonas Müller (M. Sc.) ; organized by: Institute for Automotive Engineering (RWTH Aachen University), Institute for Combustion Engines (RWTH Aachen University)*, Aachen, 2021, Institute for Automotive Engineering, RWTH Aachen University, pp. 595-614.

Integration of a Vehicle Operating Mode Management into UNICARagil's Automotive Service-oriented Software Architecture

Bibtex entry :

```
@inproceedings { JSG+21,  
  author = { Jatzkowski, Inga and Stolte, Torben and Graubohm, Robert  
and  
  Maurer, Markus and Kampmann, Alexandru and Alrifaae, Bassam  
and Kowalewski, Stefan and Buchholz, Michael and Dietmayer,  
Klaus },  
  title = { Integration of a Vehicle Operating Mode Management into  
UNICARagil's Automotive Service-oriented Software  
Architecture },  
  booktitle = { 30. Aachen Colloquium Sustainable Mobility : October  
4th-6th, 2021 / scientific management: Univ.-Prof. Dr.-Ing.  
Lutz Eckstein, Univ.-Prof. Dr.-Ing. Stefan Pischinger ;  
organizational management: Michaela Wacker (M. Sc.), Jonas  
M{"u"}ller (M. Sc.) ; organized by: Institute for Automotive  
Engineering (RWTH Aachen University), Institute for  
Combustion Engines (RWTH Aachen University) },  
  publisher = { Institute for Automotive Engineering, RWTH Aachen  
University },  
  pages = { 595-614 },  
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http://publications.rwth-aachen.de/record/840892/files/840892.pdf },  
}
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[KSM+21]

[PDFBIB](#)

Kloock, M. M., Scheffe, P., Maczizewski, J., Kampmann, A., Mokhtarian, A., Kowalewski, S., and Alrifaae, B., "Cyber-Physical Mobility Lab : An Open-Source Platform for Networked and Autonomous Vehicles", in *Proc. 2021 European Control Conference (ECC)*, [Piscataway, NJ], 2021, IEEE, pp. 1937-1944.

Cyber-Physical Mobility Lab : An Open-Source Platform for Networked and Autonomous Vehicles

Bibtex entry :

```
@inproceedings { KSM+21,  
  author = { Kloock, Maximilian Martin and Scheffe, Patrick and  
    Maczijekowski, Janis and Kampmann, Alexandru and Mokhtarian,  
    Armin and Kowalewski, Stefan and Alrifaae, Bassam },  
  title = { Cyber-Physical Mobility Lab : An Open-Source Platform for  
    Networked and Autonomous Vehicles },  
  booktitle = { 2021 European Control Conference (ECC) },  
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  pages = { 1937-1944 },  
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  organization = { 2021 European Control Conference, online,  
2021-06-29 -  
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[MKL+21]

[PDFBIB](#)

Mokhtarian, A., Kampmann, A., Lüer, M., Kowalewski, S., and Alrifaae, B., "A Cloud Architecture for Networked and Autonomous Vehicles", *IFAC-PapersOnLine*, vol. 54, iss. 2, pp. 233-239, 2021

A Cloud Architecture for Networked and Autonomous Vehicles

Bibtex entry :

```
@article { MKL+21,  
  author = { Mokhtarian, Armin and Kampmann, Alexandru and L{"u}er,  
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  pages = { 233-239 },  
  volume = { 54 },  
  number = { 2 },  
  year = { 2021 },  
  address = { Frankfurt },  
  issn = { 2405-8963 },  
  organization = { 16. IFAC Symposium on Control in Transportation  
Systems,  
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  doi = { 10.1016/j.ifacol.2021.06.028 },
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http://publications.rwth-aachen.de/record/828696/files/828696.pdf },
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[KMR+20]

[PDFBIB](#)

Kampmann, A., Mokhtarian, A., Rogalski, J., Kowalewski, S., and Alrifaae, B., "Agile Latency Estimation for a Real-time Service-oriented Software Architecture", *IFAC-PapersOnLine*, vol. 53, iss. 2, pp. 5795-5800, 2020

Agile Latency Estimation for a Real-time Service-oriented Software Architecture

Bibtex entry :

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@article { KMR+20,
  author = { Kampmann, Alexandru and Mokhtarian, Armin and Rogalski,
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Software Architecture },
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  volume = { 53 },
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  year = { 2020 },
  address = { Frankfurt ; M{"u"}nchen [u.a.] },
  issn = { 2405-8963 },
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Meeting
Societal Challenges, Berlin (Germany), 2020-07-11 -
2020-07-17 },
  doi = { 10.1016/j.ifacol.2020.12.1619 },
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http://publications.rwth-aachen.de/record/822016/files/822016.pdf },
}
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[LvW+20]

[PDFBIB](#)

Lampe, B., van Kempen, R., Woopen, T., Kampmann, A., Alrifaae, B., and Eckstein, L., "Reducing Uncertainty by Fusing Dynamic Occupancy Grid Maps in a Cloud-based Collective Environment Model", in *Proc. 2020 IEEE Intelligent Vehicles Symposium (IV) / publisher: IEEE, Piscataway, NJ, 2020, IEEE, pp. 837-843.*

Reducing Uncertainty by Fusing Dynamic Occupancy Grid Maps in a Cloud-based Collective Environment Model

Bibtex entry :

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@inproceedings { LvW+20,  
  author = { Lampe, Bastian and van Kempen, Raphael and Woopen, Timo  
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  Kampmann, Alexandru and Alrifaae, Bassam and Eckstein, Lutz },  
  title = { Reducing Uncertainty by Fusing Dynamic Occupancy Grid  
Maps  
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  booktitle = { 2020 IEEE Intelligent Vehicles Symposium (IV) /  
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  IEEE },  
  publisher = { IEEE },  
  pages = { 837-843 },  
  year = { 2020 },  
  address = { Piscataway, NJ },  
  organization = { 31. IEEE Intelligent Vehicles Symposium, online,  
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  - 2020-11-13 },  
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  url = { http://publications.rwth-aachen.de/record/815706 },  
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[LvW+20a]

[PDFBIB](#)

Lampe, B., van Kempen, R., Woopen, T., Kampmann, A., Alrifaae, B., and Eckstein, L., "Reducing Uncertainty by Fusing Dynamic Occupancy Grid Maps in a Cloud-based Collective Environment Model", , p. 7, 2020

Reducing Uncertainty by Fusing Dynamic Occupancy Grid Maps in a Cloud-based Collective Environment Model

Bibtex entry :

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@article { LvW+20a,  
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http://publications.rwth-aachen.de/record/817686/files/817686.pdf },
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[MKA+20]

PDFBIB

Mokhtarian, A., Kampmann, A., Alrifaae, B., Kowalewski, S., Lampe, B., and Eckstein, L., "Agile Requirement Engineering for a Cloud System for Automated and Networked Vehicles", in *Proc. 2nd International Workshop on Autonomous Systems Design : ASD 2020, March 13, 2020, Grenoble, France, converted to a virtual event due to COVID-19, held in April 2020 / edited by Sebastian Steinhorst, Jyotirmoy V. Deshmukh*, Saarbrücken/Wadern, Germany, 2020 in OpenAccess Series in Informatics, Schloss Dagstuhl - Leibniz-Zentrum für Informatik GmbH, Dagstuhl Publishing, August, p. 4:1-4:8.

Agile Requirement Engineering for a Cloud System for Automated and Networked Vehicles

Bibtex entry :

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@inproceedings { MKA+20,
  author = { Mokhtarian, Armin and Kampmann, Alexandru and Alrifaae,
    Bassam and Kowalewski, Stefan and Lampe, Bastian and
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  title = { Agile Requirement Engineering for a Cloud System for
    Automated and Networked Vehicles },
  booktitle = { 2nd International Workshop on Autonomous Systems
Design :
    ASD 2020, March 13, 2020, Grenoble, France, converted to a
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    by Sebastian Steinhorst, Jyotirmoy V. Deshmukh },
  publisher = { Schloss Dagstuhl - Leibniz-Zentrum für Informatik
GmbH,
    Dagstuhl Publishing, August },
  pages = { 4:1-4:8 },
  series = { OpenAccess Series in Informatics },
  year = { 2020 },
  address = { Saarbrücken/Wadern, Germany },
  organization = { 2. International Workshop on Autonomous Systems
Design,
    Grenoble (France), 2020-03-12 - 2020-03-13 },
  doi = { 10.4230/OASIS.ASD.2020.4 },
  typ = { PUB:(DE-HGF)7 },
  reportid = { RWTH-2020-08417 },
  cin = { 122810 / 120000 / 414110 },
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[MKA+20a]

[PDFBIB](#)

Mokhtarian, A., Kampmann, A., Alrifaae, B., and Kowalewski, S., "The Dynamic Service-oriented Software Architecture for the UNICARagil Project", in *Proc. 29. Aachen Colloquium Sustainable Mobility : October 5th-7th, 2020, digital event / scientific management: Univ.-Prof. Dr.-Ing. Lutz Eckstein, Univ.-Prof. Dr.-Ing. Stefan Pischinger ; organizational management: Michaela Wacker (M. Sc.), Jonas Müller (M. Sc.) ; organized by: Institute for Automotive Engineering, RWTH Aachen University; Institute for Combustion Engines, RWTH Aachen University. - 1: October 6th, 2020, Aachen, 2020, Institute for Automotive Engineering, RWTH Aachen University ; Aachen : Institute for Combustion Engines, RWTH Aachen University, pp. 275-284.*

The Dynamic Service-oriented Software Architecture for the UNICARagil Project

Bibtex entry :

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@inproceedings { MKA+20a,
  author = { Mokhtarian, Armin and Kampmann, Alexandru and Alrifaae,
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  title = { The Dynamic Service-oriented Software Architecture for
the
  UNICARagil Project },
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  5th-7th, 2020, digital event / scientific management:
  Univ.-Prof. Dr.-Ing. Lutz Eckstein, Univ.-Prof. Dr.-Ing.
  Stefan Pischinger ; organizational management: Michaela
  Wacker (M. Sc.), Jonas M{"u}ller (M. Sc.) ; organized by:
  Institute for Automotive Engineering, RWTH Aachen
  University; Institute for Combustion Engines, RWTH Aachen
  University. - 1: October 6th, 2020 },
  publisher = { Institute for Automotive Engineering, RWTH Aachen
University
  ; Aachen : Institute for Combustion Engines, RWTH Aachen
  University },
  pages = { 275-284 },
  year = { 2020 },
  address = { Aachen },
  organization = { 29. Aachen Colloquium Sustainable Mobility = 29.
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  Kolloquium Fahrzeug- und Motorentechnik, Aachen (Germany),
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  doi = { 10.18154/RWTH-2020-11256 },
  typ = { PUB:(DE-HGF)7 },
  reportid = { RWTH-2020-11256 },
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http://publications.rwth-aachen.de/record/807282/files/807282.pdf },
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}

[SMK+20]

[PDFBIB](#)

Scheffe, P., Maczjowski, J., Kloock, M. M., Kampmann, A., Derks, A., Kowalewski, S., and Alrifaae, B., "Networked and Autonomous Model-scale Vehicles for Experiments in Research and Education", *IFAC-PapersOnLine*, vol. 53, iss. 2, pp. 17332-17337, 2020

Networked and Autonomous Model-scale Vehicles for Experiments in Research and Education

Bibtex entry :

```
@article { SMK+20,
  author = { Scheffe, Patrick and Maczjowski, Janis and Kloock,
    Maximilian Martin and Kampmann, Alexandru and Derks, Andreas
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  publisher = { Elsevier },
  pages = { 17332-17337 },
  volume = { 53 },
  number = { 2 },
  year = { 2020 },
  address = { Frankfurt },
  issn = { 2405-8963 },
  organization = { 21. IFAC World Congress, online, 2020-07-11 -
    2020-07-17 },
  doi = { 10.1016/j.ifacol.2020.12.1821 },
  typ = { PUB:(DE-HGF)16 },
  reportid = { RWTH-2021-03987 },
  cin = { 122810 / 120000 },
  url = {
    http://publications.rwth-aachen.de/record/817552/files/817552.pdf },
}
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[KAK+19]

[PDFBIB](#)

Kampmann, A., Alrifaae, B., Kohout, M., Wüstenberg, A., Woopen, T., Nolte, M., Eckstein, L., and Kowalewski, S., "A Dynamic Service-Oriented Software Architecture for Highly Automated Vehicles", in *Proc. The 2019 IEEE Intelligent Transportation Systems Conference - ITSC : Auckland, New Zealand, 27-30 October 2019 / IEEE, IEEE-ITSC 2019, ITSS - IEEE Intelligent Transportation Systems Society, Piscataway, NJ, 2019, IEEE*, pp. 2101-2108.

A Dynamic Service-Oriented Software Architecture for Highly Automated Vehicles

Bibtex entry :

```
@inproceedings { KAK+19,  
  author = { Kampmann, Alexandru and Alrifaae, Bassam and Kohout,  
Markus  
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Marcus and Eckstein, Lutz and Kowalewski, Stefan },  
  title = { A Dynamic Service-Oriented Software Architecture for  
Highly  
Automated Vehicles },  
  booktitle = { The 2019 IEEE Intelligent Transportation Systems  
Conference  
- ITSC : Auckland, New Zealand, 27-30 October 2019 / IEEE,  
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[KNR+19]

[PDFBIB](#)

Keilhoff, D., Niedballa, D., Reuss, H., Buchholz, M., Gies, F., Dietmayer, K., Lauer, M., Stiller, C., Ackermann, S., Winner, H., Kampmann, A., Alrifaae, B., Kowalewski, S., Klein, F., Struth, M. M., Woopen, T., and Eckstein, L., "UNICARagil - New architectures for disruptive vehicle concepts", in *Proc. 19. Internationales Stuttgarter Symposium : Automobil- und Motorentechnik / Michael Bargende, Hans-Christian Reuss, Andreas Wagner, Jochen Wiedemann (Hrsg.)*, Wiesbaden ; [Heidelberg], 2019 in Proceedings, Springer Vieweg, pp. 830-842.

UNICARagil - New architectures for disruptive vehicle concepts

Bibtex entry :

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@inproceedings { KNR+19,  
  author = { Keilhoff, Dan and Niedballa, Dennis and Reuss,  
Hans-Christian and Buchholz, Michael and Gies, Fabian and  
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and Ackermann, Stefan and Winner, Hermann and Kampmann,  
Alexandru and Alrifaae, Bassam and Kowalewski, Stefan and  
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[KWA+19]

[PDFBIB](#)

Kampmann, A., Wüstenberg, A., Alrifaae, B., and Kowalewski, S., "A Portable Implementation of the Real-Time Publish-Subscribe Protocol for Microcontrollers in Distributed Robotic Applications", in *Proc. The 2019 IEEE Intelligent Transportation Systems Conference - ITSC : Auckland, New Zealand, 27-30 October 2019 / IEEE, IEEE-ITSC 2019, ITSS - IEEE Intelligent Transportation Systems Society*, Piscataway, NJ, 2019, IEEE, pp. 443-448.

A Portable Implementation of the Real-Time Publish-Subscribe Protocol for Microcontrollers in Distributed Robotic Applications

Bibtex entry :

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@inproceedings { KWA+19,
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[WLB+18]

[PDFBIB](#)

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UNICARagil - Disruptive Modular Architectures for Agile, Automated Vehicle Concepts

Bibtex entry :

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@inproceedings { WLB+18,
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Dominik and Katzenbeisser, Stefan and Leinen, Stefan and
Becker, Matthias and Stiller, Christoph and Furmans, Kai and
Bengler, Klaus and Diermeyer, Frank and Lienkamp, Markus and
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Univ.-Prof. Dr.-Ing. Stefan Pischinger ; organizational
management: Benedikt Hammer{"u"}ller (M. Sc.), Dipl.-Ing.
Rainer Wolsfeld ; organized by: Institute for Automotive
Engineering (RWTH Aachen), Institute for Combustion Engines
(RWTH Aachen) },
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[KGK17]

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Kalkov, I., Gurchian, A., and Kowalewski, S., "Explicit prioritization of parallel Intent broadcasts in real-time Android", in *Proc. Concurrency and computation*, Chichester, 2017, vol. 29, Wiley.

Explicit prioritization of parallel Intent broadcasts in real-time Android

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@inproceedings { KGK17,
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[KGK15]

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[KGK14]

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Predictable Broadcasting of Parallel Intents in Real-Time Android

Bibtex entry :

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