Softwareproject-lab "NXT-Programming"

In our this year's softwareproject-practical training, students implemented their own control software as well as a remote control for balanced two-wheel Lego-Robots. Amongst the implemented compulsory requirements was a grafical user interface with different interaction possibilities and a navigation display. Additionally, the participants put a range of their own ideas into practice, for example a sensor-based control with an Android-mobile phone.



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